

HANDLY & FREQUENTLY USED FORMULAS FOR THERMAL ENGINEERS

GEOMETRY & MATH | GEOMETRI & MATEMATIK

Cylindrical (Tube) Volume $V = p / 4 \cdot d^2 \cdot L$ [m³]

Cylindrical (Tube) Surface $A = p \cdot d \cdot L$ [m²]

Diameter $d = \sqrt{4 \cdot A / p}$ [m]

Rectangular Triangle A = 90°: Geometrical Vector Sum

$$a^2 = b^2 + c^2 \quad \hat{U} \quad a = \sqrt{b^2 + c^2} \quad [\text{m}]$$

$$\cos B = c / a \quad ; \quad \sin B = b / a \quad ; \quad \tan B = b / c$$

STRENGTH & STATICS | STYRKELÆRE & STATIK

Force $\mathbf{F} = m \cdot a$ [N]

Stress $\mathbf{s} = \mathbf{F} / \mathbf{A}$ [N/m²]

Stress $\mathbf{s} = \mathbf{e} \cdot \mathbf{E}$ [N/m²] Hook's Law

Strain $\mathbf{e} = \mathbf{DL} / \mathbf{L}$ [-]

A = Cross section area [m²]

E = Elasticity Modulus [N/m²]

m = Mass [kg]

a = Acceleration / Gravity Acceleration [m/s²]

ΔL = Deformation in Length [m] ; L = Length [m]

Bending Stress in beams $\mathbf{s} = \mathbf{M}_T / \mathbf{W}$ [N/m²]

M_T = Torque [Nm]

W = Section Modulus [m³] profile depending

Simple Supported Beam – Uniform spread load

Max. torque $\mathbf{M}_{T, MAX} = \mathbf{P} \cdot \mathbf{L} / 8$ [N·m]

at middle of the beam

Max. Reflection $\mathbf{U} = 5 \cdot \mathbf{M} \cdot \mathbf{L}^2 / (48 \cdot \mathbf{E} \cdot \mathbf{I})$ [m]

at middle

Cantilever Beam – Uniform spread load

Max. torque $\mathbf{M}_{T, MAX} = \mathbf{P} \cdot \mathbf{L} / 2$ [N·m]

at the fixed support in the wall

Max. Reflection $\mathbf{U} = \mathbf{M}_{T, MAX} \cdot \mathbf{L}^2 / (4 \cdot \mathbf{E} \cdot \mathbf{I})$ [m]

at free end of the beam

P = Total uniform load of beam [N]

I = Moment of Inertia [m⁴]

HEAT & TEMPERATURES | VARME & TEMPERATUR

Absolute Temperature (Kelvin)

$$T = t + 273,15 \text{ [K]}$$

t = Temperature [°C]

Heat / Heat Content $Q = m \cdot C_p \cdot (t_2 - t_1)$ [W] | [J]

m = Mass Flow [kg/s] / Mass [kg]

C_p = Specific Heat [J/(kgK)]

t_1 and t_2 = Temperatures Inlet and Outlet [K] | [°C]

Linearly Heat Expansion of Materials

$$DL = L \cdot \alpha_L \cdot Dt \text{ [m]}$$

Volumetric Heat Expansion of Materials

$$DV = V \cdot \beta_V \cdot Dt \text{ [m}^3\text{]}$$

L = Length [m] ; V = Volume [m³]

α_L = Length Expansion Coefficient [1/°C]

β_V = Volume Expansion Coefficient [1/°C]

Δt = Temperature Change [°C]

For Ideal Gasses :

$$p \cdot v = R \cdot T = p_0 \cdot v_0 \cdot (1 + t / 273,15)$$

Specific Volume $v = 1 / \rho$ [m³/kg]

p = Pressure (bar abs.) ; ρ = Density [kg/ m³]

T = Absolute Temperature [K]

$p_0 \cdot v_0$: Pressure and Specific volume at 0°C

R = Gas Coefficient [J/(kg·K)] :

Air = 287,1 J/(kg·K) Steam = 461,5 J/(kg·K)

1 kmol equals a volume of 22,4138 m³

$$m = n \cdot M \text{ [kg]}$$

$$V_n = n \cdot V_{mol} \text{ [m}_n^3\text{]} \text{ at } 0^\circ\text{C and } 1,01325 \text{ bar}$$

$$\rho = m / V_n \text{ [kg/m}_n^3\text{]}$$

M = Mol mass [kg/mol] ; ρ = Density [kg/m_n³]

V_n = Normal Volume [m_n³] ; n = Number of mol

V_{mol} = Molar Volume [m_n³/mol] ; m = mass [kg]

HEAT TRANSFER | VARMEOVERFØRING

BY CONVECTION | VED KONVEKTION

Heat Transfer by Convection $Q = k \cdot F \cdot DJ$ [W]
F = Heat Surface – Total wall area [m²]

Heat Transmission Coefficient

$$k = 1 / (1/a_1 + 1/a_2 + e/l + f_1 + f_2) \text{ [W/(m}^2\cdot\text{K)]}$$

α_1 = Heat Transfer Coefficient – Fluid 1 [W/(m²·K)]

α_2 = Heat Transfer Coefficient – Fluid 2 [W/(m²·K)]

λ = Heat Conductivity Wall Material [W/(m·K)]

e = Wall Thickness [m]

f_1 = Fouling Coefficient – for the wall of fluid 1 [m²·K/W]

f_2 = Fouling Coefficient – for the wall of fluid 2 [m²·K/W]

BY RADIATION | VED STRÅLING

Radiation Heat between two surfaces 1 and 2

$$F = C_{12} \cdot F_1 \cdot ((T_1/100)^4 - (T_2/100)^4) \text{ [W]}$$

Radiation Coefficient

$$C_{12} = 1 / (1/C_1 + 1/C_2 - 1/C_s) \text{ [W/(m}^2\cdot\text{K)]}$$

$$C = \epsilon \cdot C_s \text{ [W/(m}^2\cdot\text{K)]}$$

ϵ = Emission ratio [-]

C_s = Radiation Coefficient for the absolute black surface [-]

T = Absolute temperature [K]

Logarithmic Middle Temperature Difference

$$DJ = (Dt_1 - Dt_2) / \ln (Dt_1/Dt_2) ; \text{ all values in [K] | [}^\circ\text{C]}$$

Δt_1 = Difference in Temperatures of Fluid1 and Fluid 2 at “1”

Δt_2 = Difference in Temperatures of Fluid1 and Fluid 2 at “2”
“1” and “2” being the physical positions of the inlets and outlets of heat exchanger in current or counter flow types

Nusselt's Number

$$Nu = a \cdot L_F / \lambda \quad [-] \quad \hat{U} = a \cdot L_F / L_F$$

α = Heat Transfer Coefficient [W/(m²·K)]

L_F = Flow Length [m] e.g. diameter or plate length

λ = Heat Conductivity Fluid [W/(m·K)]

General expression for forced circulation

$$Nu = K_1 \cdot Re^{K_2} \cdot Pr^{K_3}$$

General expression for natural circulation

$$Nu = K_5 \cdot Gr^{K_4} \cdot Pr^{K_3}$$

Prandtl's Number $Pr = r \cdot C_p \cdot \rho / \lambda \quad [-]$

Grashoff's Number $Gr = g \cdot r \cdot \rho \cdot \Delta T \cdot L_F^3 / \mu \quad [-]$

g = Gravity acceleration [m/s²]

K_1, K_2, K_3, K_4 and K_5 are different constants and equations based on tests and depending on the type of heat transfer.

MECHANICS OF FLUIDS | STRØMNING & VÆSKEFYSIK

Total pressure $p_T = p_s + p_D$ [N/m²]

Dynamic pressure $p_D = \frac{1}{2} \cdot c^2 \cdot r$ [N/m²]

Pressure Height $p_H = g \cdot r \cdot H$ [N/m²]

p_s = Static pressure [N/m²]

g = Gravity acceleration [m/s²]

H = Height / Altitude [m]

Bernoulli's Law about constancy in pressure. All in [N/m²]

$$p_{s,1} + p_{D,1} + p_{H,1} = p_{s,2} + p_{D,2} + p_{H,2} \quad \hat{U}$$
$$p_{s,1} + \frac{1}{2} \cdot c_1^2 \cdot r + g \cdot r \cdot H_1 = p_{s,2} + \frac{1}{2} \cdot c_2^2 \cdot r + g \cdot r \cdot H_2$$

For Ideal Gasses:

Dynamic Viscosity $h @ h_0 \cdot (273 + t) / 273$ [N·s/m²]

t = Temperature [°C]

Dynamic Viscosity $h = n \cdot r$ [Pa·s] | [kg/(m·s)]

Reynold's Number $Re = c \cdot L_F / \nu$ [-]

ν = Kinematic Viscosity [m²/s]; ρ = Density [kg/m³]

c = Velocity [m/s]; L_F = Flow Length [m]

Pressure Drop in tube $\Delta p_{TB} = \lambda \cdot p_D \cdot L_T / d$
 $= \lambda \cdot \frac{1}{2} \cdot r \cdot c^2 \cdot L_T / d$ [N/m²]

λ = Friction Coefficient [-]; L_T = Tube Length [m]

d = Internal Tube Diameter [m]; ρ = Density [kg/m³]

c = Velocity [m/s]

Pump Capacity $P = h_T \cdot q_V \cdot \Sigma \Delta p$ [W]

Total Efficiency $h_T = (h_{PUMP} \cdot h_{MOTOR})$

Efficiency $h = P_{PERFORMED} / P_{ABSORB}$

q_V = Volume flow [m³/s]

$\Sigma \Delta p$ = Sum of all pressure drops in the circuit [Pa]

ELECTRICITY | ELECTRICITET

Power / Capacity of a 1-Phase System :

$$P = U_{PH} \cdot I_{PH} \text{ [W]}$$

Power / Capacity of a 3-Phase System :

$$P = \sqrt{3} \cdot U_N \cdot I_N \cdot \cos \varphi \text{ [W]}$$

U_N = Net Voltage [V] ; I_N = Net Current [A]

U_{PH} = Phase Voltage [V] ; I_{PH} = Phase Current [A]

$\cos \varphi$ = Phase Angel [-]

$\cos \varphi = 1$ for Heating elements and other simple resist.

$\cos \varphi < 1$ for Electrical Motors (inductive resistance).

Power, Voltage and Current in Conventional Resistances

Ohm's Law

$$U = R \cdot I \text{ [V]}$$

Power expressed by the resistance

$$P = U \cdot I = U^2 / R = I^2 \cdot R \text{ [W]}$$

U = Voltage [V] ; I = Current [A]

R = Resistance [Ω] | [Ohm]